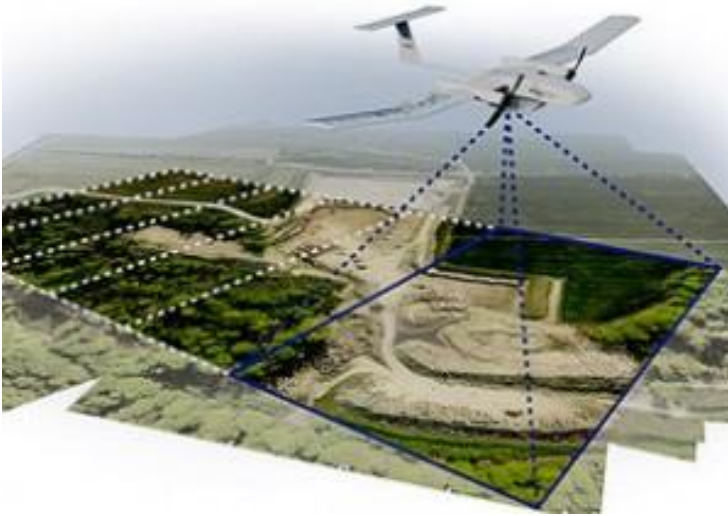


UAV Aerial Survey for Large Scale Map Updating

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SEAS Congress 15-17 August 2017
Bandar Seri Begawan, Brunei
Darussalam



Background

- JUPEM, sole national government mapping; 4800 personnel, Annual Budget US80 millions;
- **Map Update Policy at 3, 5 and 10 years interval for Topographic maps;**
- Updating focussed in developed, urban and rural part;
- **Updating using MAV are tedious, timely and costly**
- Cloudy weather & wasted images captured
- **Integrate UAV orthophoto with existing orthophoto**
- UAV can fly under the cloud and cheaper cost



Background

- The use UAV orthophotos are investigated issues of map updating.
- UAV technology can be used to update existing orthophoto previously generated from MAV platform.
- Integrate new orthophoto with existing to yield single orthophoto output.
- The process was implemented by cut and append, and cautiously assemble parts of them.
- This new updated orthophoto should be usable to form a image to update topographic map.

Study area at Kampung Laya-Laya, Tuaran, Sabah, Malaysia



Orthophotos taken using MAV Feb 2014 (left) and via UAV system in Sept 2016 (right)

Dataset of the vector map sheet of the study area produced through digital mapping.

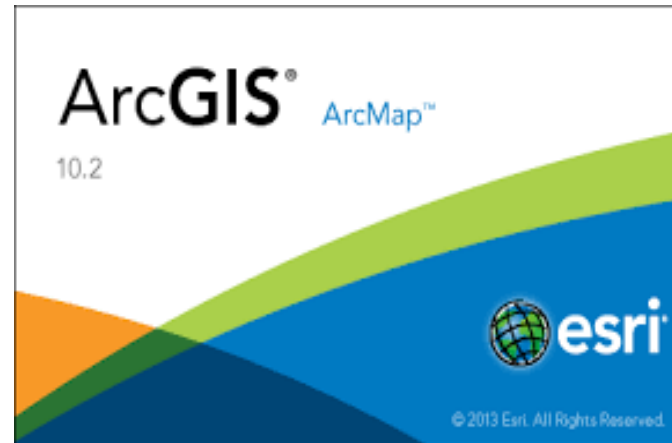


Equipment



- Digital aerial camera Vexcel UltraCam Eagle 80 captured images with 60% front overlap and 50% side overlap.
- Ground Sample Distance (GSD) was set to 10cm. Rectified Skew Orthomorphic (RSO) was applied. GDM 2000 reference datum.
- A series of aerial photography were taken on 21 September 2016 along a stretch of area 2km x 2 km
- We used a UAV eBEE RTK, employing camera Sony Cybershot DSC-WX 220 RGB 18.2 MP.
- GSD was set at 8.3cm with flying height of 600 feet with needed overlap capture

Equipment and Software



HALE, MID-RANGE and MICRO



Flow chart of the photograph aerial acquisition and geospatial data updating process.

Rectified Skew Orthomorphic (RSO)
East Malaysia coordinates system and
GDM2000 Malaysia as datum

3 colour bands of blue,
green and red

Aerial Photographs

Existing Orthophoto

UAV Image

Orthophoto UAV

Overlay (Cut and Append)

Mosaic Orthophoto

Overlay with Existing Dataset

Updating and Digitisation

New Updated Map

Coordinate system of
UTM Zone 50N and WGS84 as datum.
4 colour bands, i.e. blue, green, red, near infrared

similar colour bands in order to
obtain a single raster image;
eliminate the fourth band,
near-infrared

Conversion of 4 bands to 3
bands

Transformation of Coordinate
System

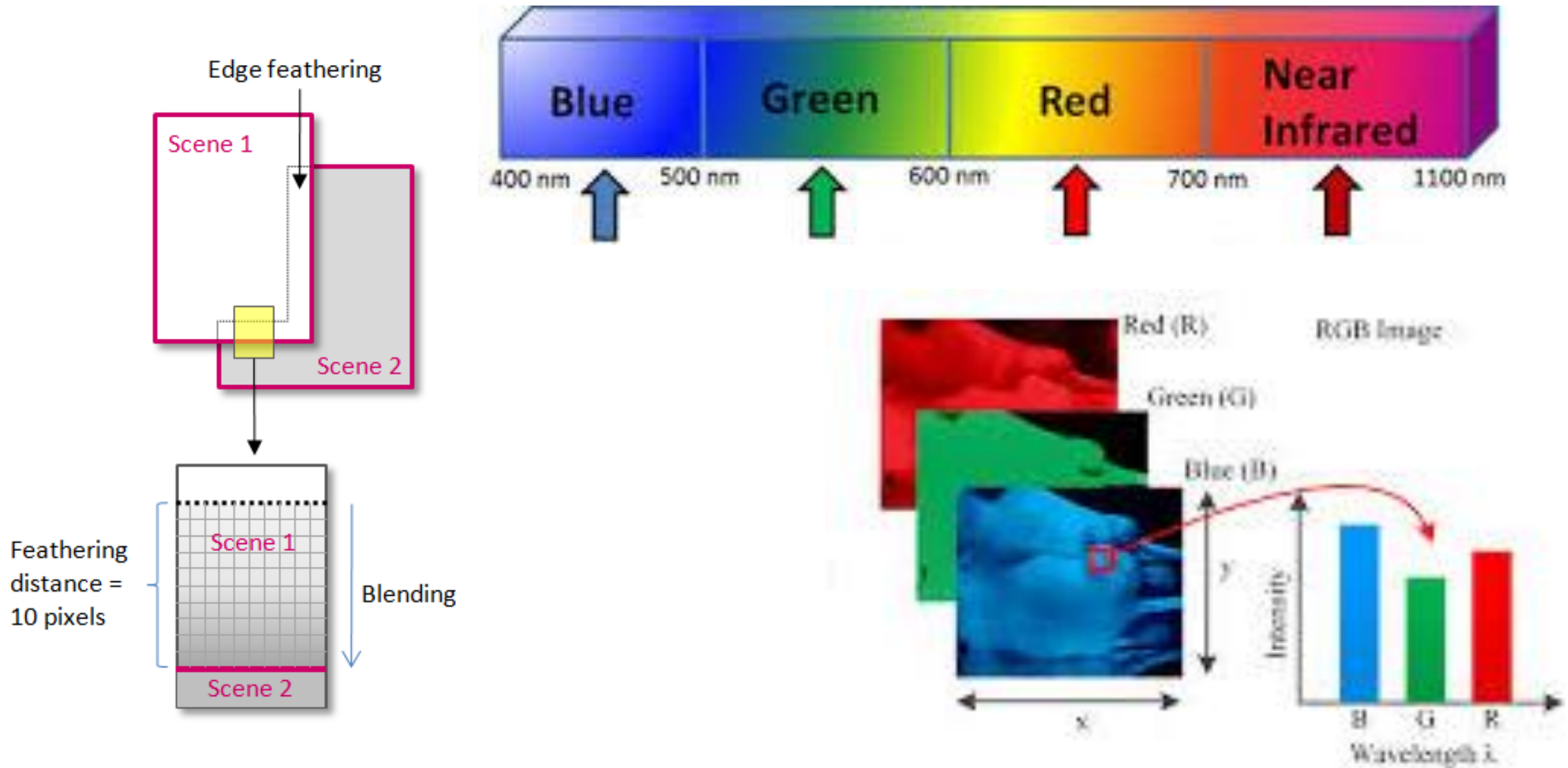
RSO East Malaysia with
GDM2000 Malaysia as the
reference datum.



Seamless mosaic interface

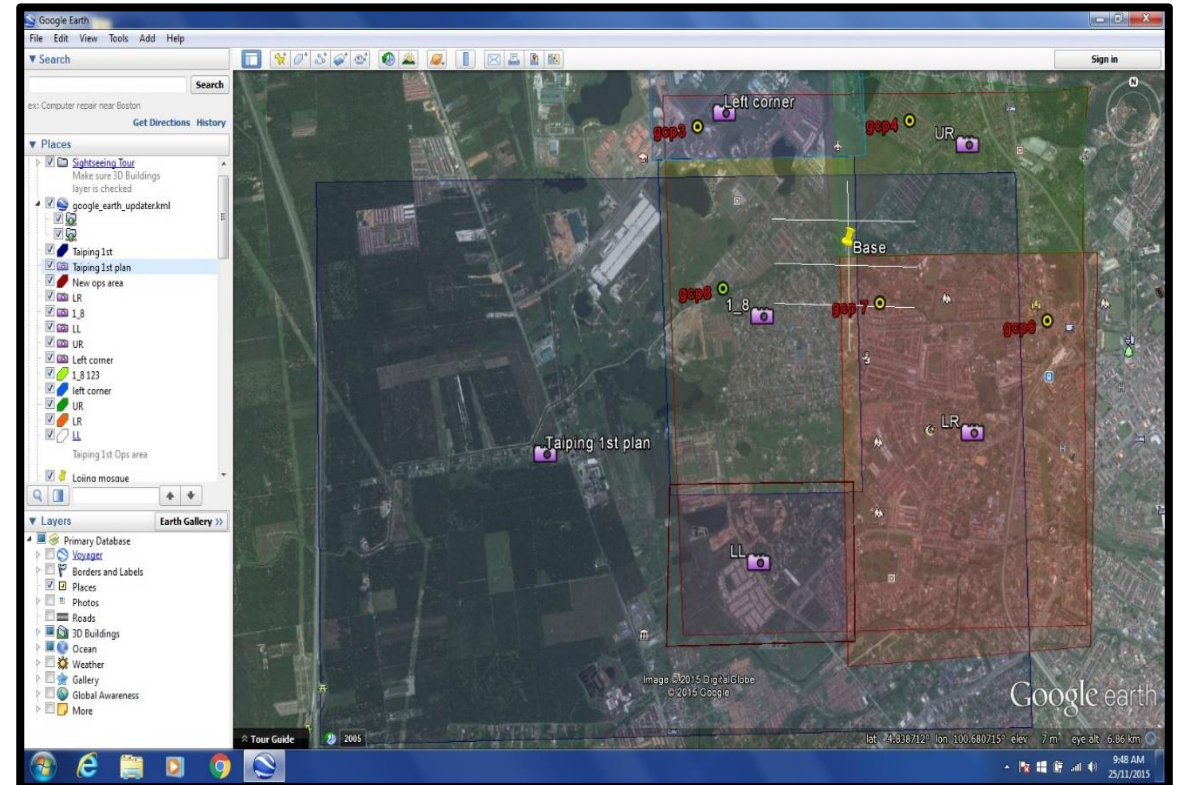
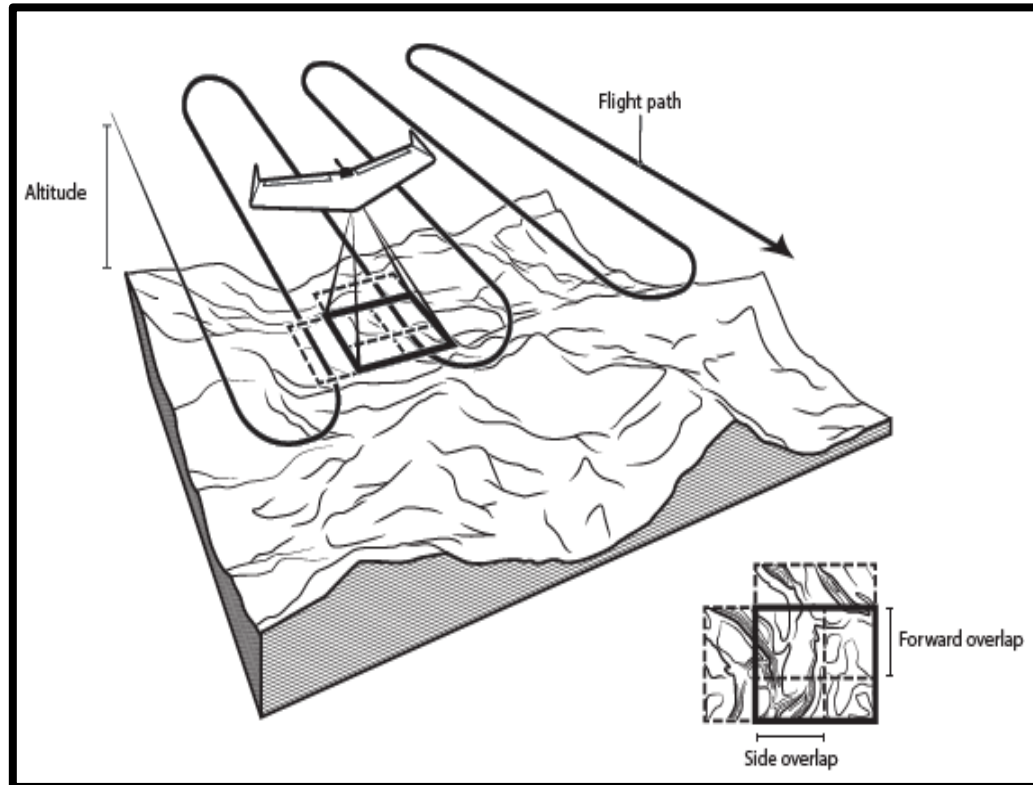


Layer stacking in ENVI 5.2 & Edge Matching



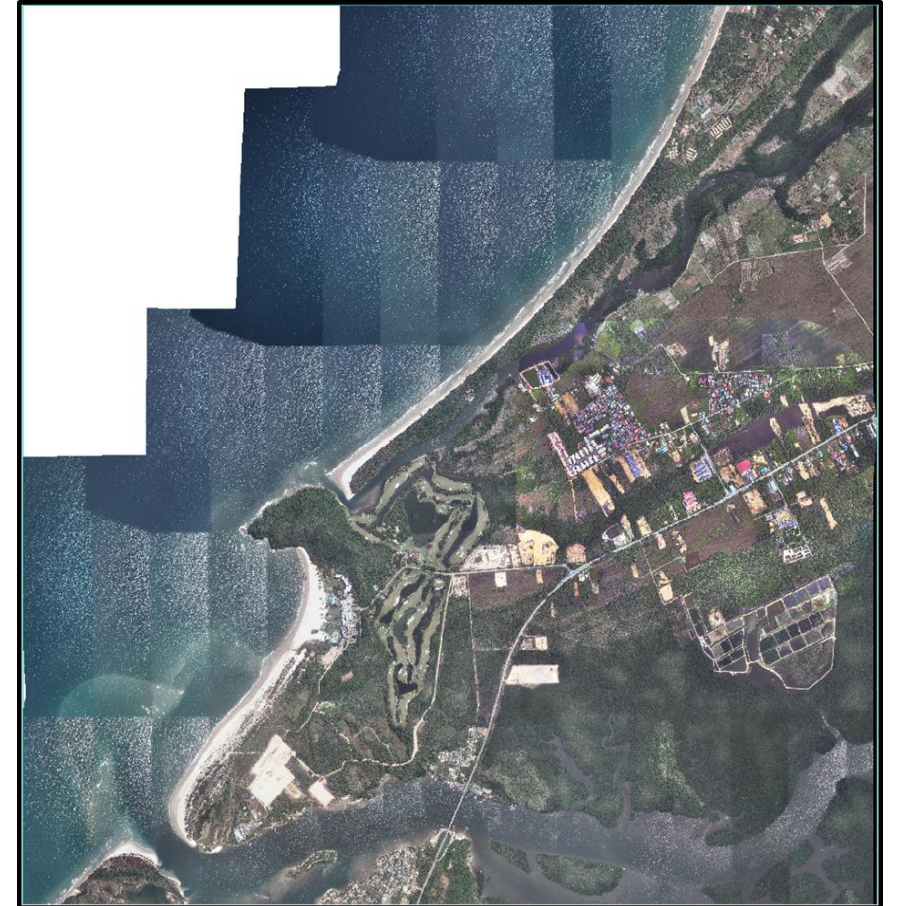
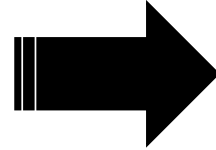
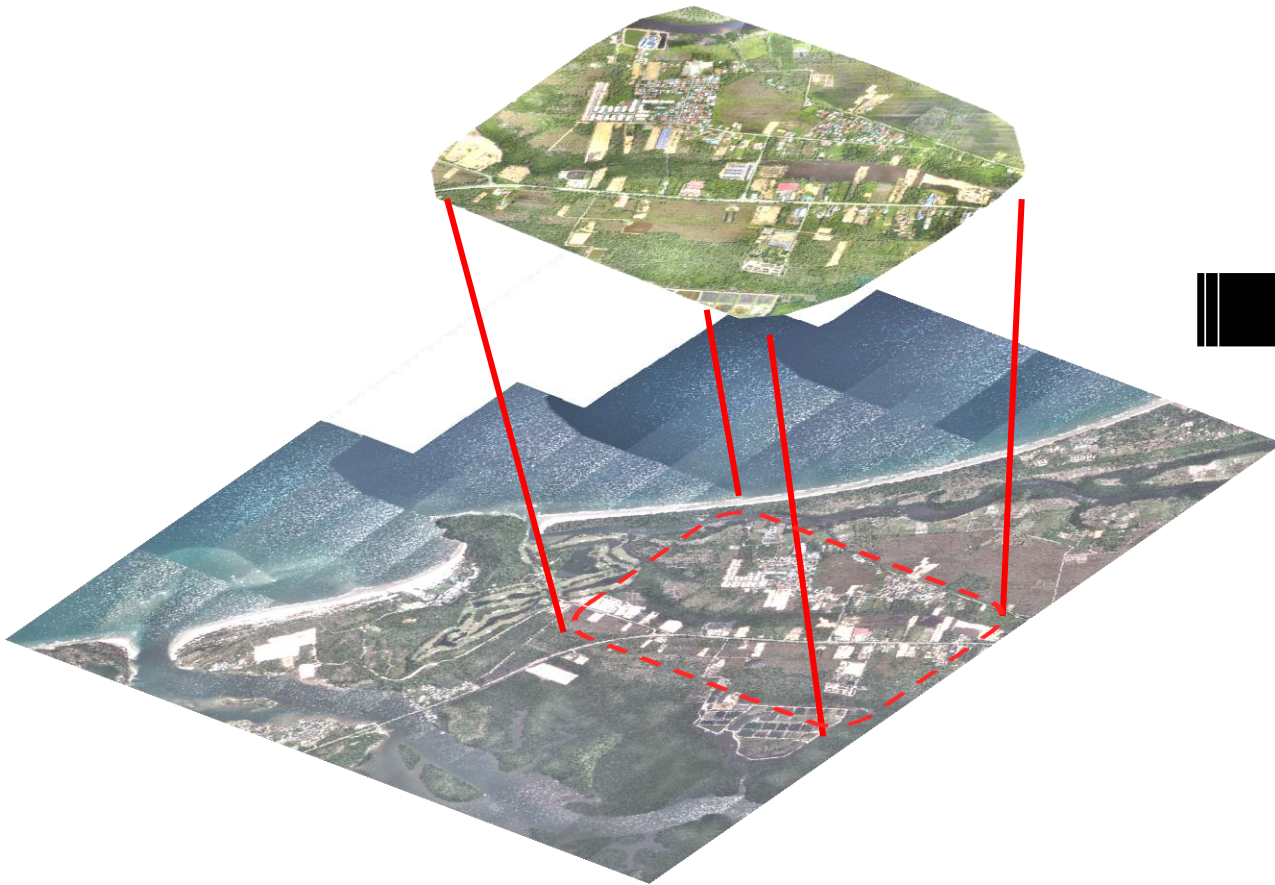
The UAV Flight

80% forward and 60% side overlapped– 600 ft height



It took about 40 min using two eBee UAV for 4.3km

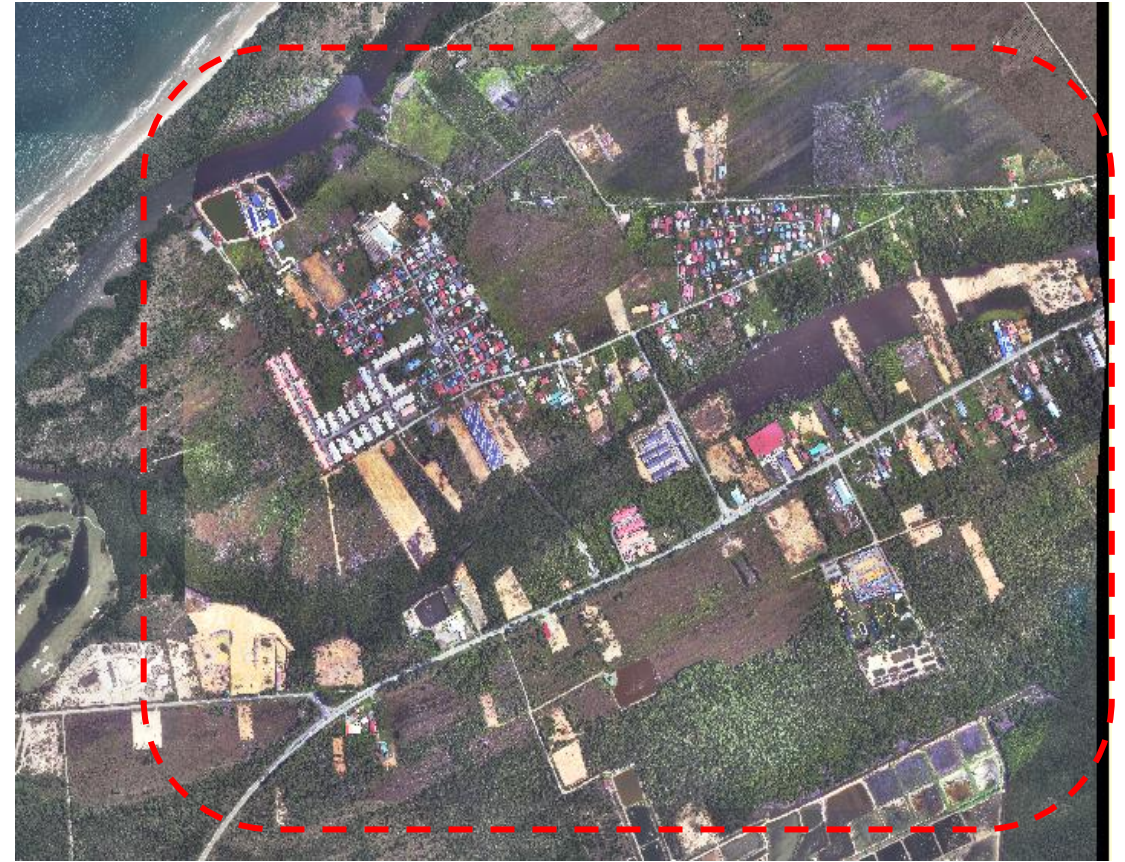
➡ Mosaicking to produce single raster image



Outcome and Analysis



Before Mosaicking

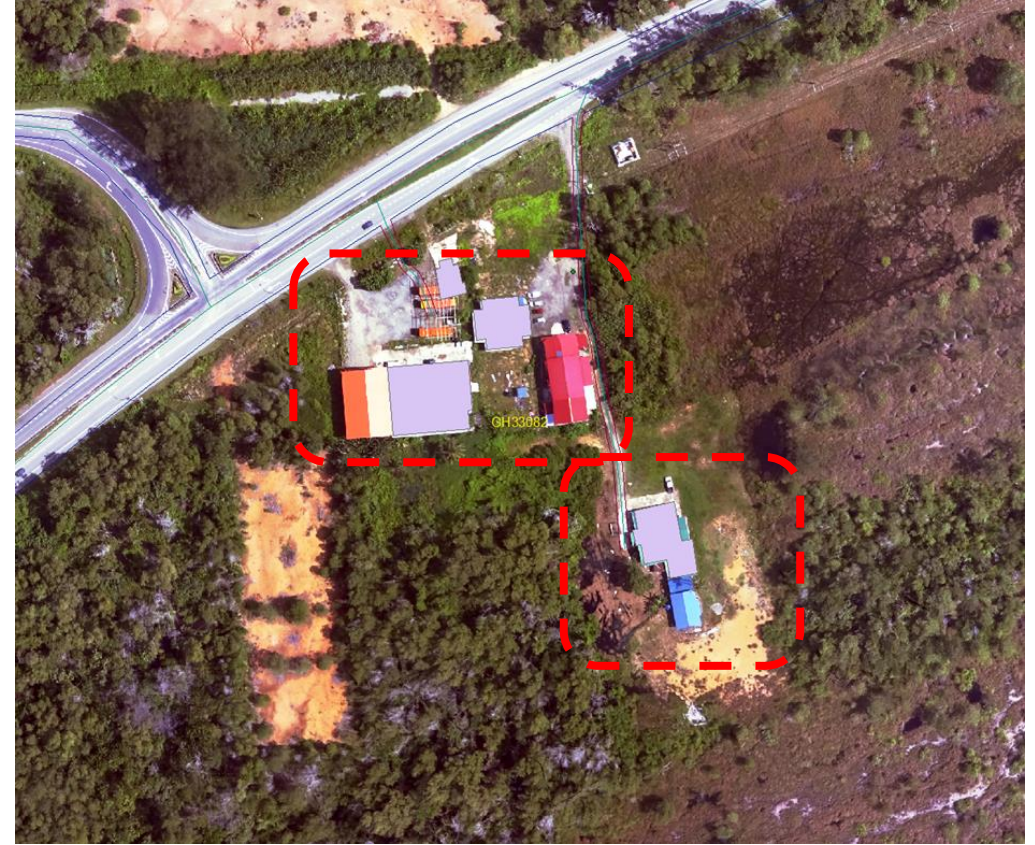


After Mosacking

Outcome and Analysis



Before Mosaicking



After Mosacking

Outcome and Analysis



Before Mosaicking



After Mosacking

Digitization; New features identified were digitized as new spatial objects that would be used to update map sheets

EXISTING ORTHOPHOTO	MOSAICKED ORTHOPHOTO	DETAILS DIGITIZED
		<ol style="list-style-type: none">1. Lake area amended and updated2. Swamp area amended and updated3. Mangrove forest amended and updated4. Cleared land amended and updated5. Scrub/Shrub (bushes) amended and updated6. New residential buildings added7. Substation & Switching Station added8. Fence Line inserted9. Irrigation Canal added10. Culvert added11. Road Line added12. Road Edge line added13. Road Surface polygon added14. Footpath (Recreational) added

Results

- Deployed UAV has successfully to generate new orthophoto. The software Pix4UAV showed orthophoto production conformed the accuracy requirement for town
- UAV orthophoto was integrated with existing MAV orthophoto previously produced.
- Integration by means of mosaicking was carried out very well and a new mosaicked orthophoto provided for map updating.
- Quick result for a large scale map of 1:5000 around apparent area of changes.
- Fly low below the cloud is rewarding comparing to normal aircraft.
- Future plan; Vertical take-off type of UAV system with higher capability

UAV vs MAV in Aerial Mapping

		Manned Aircraft	eBee RTK UAV
No.	Element	Summary (Comparison)	
1.	Installation	Very expensive; 1. Aircraft rental 2. Camera systems 3. Customs aircraft 4. Aviation law	Inexpensive; 1. Ultra-light weight radio control aircraft 2. Digital compact camera
2.	Operation	Very expensive; 1. Need for pro pilot 2. Airport runway 3. Camera system calibration	Inexpensive; 1. Mobile 2. Do not need for runway 3. Easy setup
3.	Area	1. Cost effective for large mapping area bad for small area 2. Cost per km ² is high 3. Processing cost per km ² is Cheaper	1. Cost effective for small area and bad for large area 2. Cost per km ² is cheaper 3. Processing cost per km ² is slightly higher
4.	Application	For mapping small scale base map (scale up to 1:50,000)	1. Updating large scale map 2. Boundary/island monitoring & watch 3. Natural disaster monitoring

Analysis of images accuracy captured by MAV and UAV as compared to observed true coordinates using GNSS. Standard deviation of the differences between the two images coordinate are acceptable in the mapping accuracy of features to be plotted at large scale of 1: 10,000. The planimetric displacement allowable for smaller than 1: 20,000 scale map is 1/30 inches (0.85mm), within JUPEM's Procedure of Survey for Map Accuracy. RMSE has shown high value (1.416) when comparing coordinates of UAV versus MAV image.

Station No.	Coordinates of Orthophoto MAV		Observed Coordinates		Coordinates of Orthophoto UAV		Difference of Coordinates between Observed and Orthophoto MAV			Difference of Coordinates between Observed and Orthophoto UAV			Difference of Coordinates between Orthophoto MAV dan Orthophoto UAV		
	North	East	North	East	North	East	North	East	Magnitude	North	East	Magnitude	North	East	Magnitude
TK01	681746.128	718372.504	681745.442	718372.72	681745.943	718373.086	-0.686	0.216	0.719	-0.501	-0.366	0.620	0.185	-0.582	0.611
TK02	682247.446	719426.712	682246.882	719426.862	682246.017	719427.109	-0.564	0.150	0.583	0.865	-0.247	0.900	1.429	-0.397	1.483
TK03	682361.859	719559.253	682361.232	719559.423	682360.340	719559.493	-0.627	0.170	0.650	0.892	-0.070	0.895	1.519	-0.240	1.538
TK04	681996.365	719742.326	681995.754	719742.317	681994.989	719742.723	-0.611	-0.009	0.611	0.765	-0.406	0.866	1.376	-0.397	1.432
TK05	682579.787	720088.241	682579.076	720088.259	682578.622	720088.294	-0.711	0.018	0.711	0.454	-0.035	0.455	1.164	-0.053	1.165
TK06	682427.473	718364.931	682426.837	718364.784	682426.494	718365.566	-0.636	-0.147	0.652	0.343	-0.782	0.854	0.979	-0.635	1.167
TK07	682891.892	718249.253	682891.295	718249.394	682890.834	718250.523	-0.597	0.141	0.613	0.461	-1.129	1.220	1.058	-1.270	1.653
TK08	682837.963	718599.391	682837.22	718599.523	682836.402	718600.079	-0.743	0.132	0.754	0.818	-0.556	0.989	1.561	-0.688	1.706
TK09	682689.482	718669.372	682688.711	718669.377	682688.026	718670.060	-0.771	0.005	0.771	0.685	-0.683	0.967	1.455	-0.688	1.610
TK10	682514.375	718523.851	682513.74	718523.89	682513.184	718524.618	-0.635	0.039	0.636	0.556	-0.728	0.916	1.191	-0.767	1.416
TK11	682565.224	718735.666	682564.382	718735.634	682564.060	718736.275	-0.842	-0.032	0.843	0.322	-0.641	0.717	1.164	-0.609	1.314
TK12	682748.088	718441.527	682747.513	718441.623	682746.659	718442.321	-0.575	0.096	0.582	0.854	-0.698	1.103	1.429	-0.794	1.634
TK13	682605.678	718295.359	682605.162	718295.469	682604.646	718296.179	-0.516	0.110	0.528	0.516	-0.710	0.878	1.032	-0.820	1.318

Average	-0.213	0.022	0.216	0.176	-0.176	0.284	0.389	-0.198	0.451
Value Maximum	0.000	0.216	0.843	0.892	0.000	1.220	1.561	0.000	1.706
Value Minimum	-0.842	-0.147	0.000	-0.501	-1.129	0.000	0.000	-1.270	0.000
Std Deviation			0.316			0.424			0.670
RMSE			0.671			0.895			1.416
% Precision			100%			100%			100%





THANK YOU

FOR LISTENING TO MY IDEAS